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An Engine for Nanochemistry

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ABSTRACT

The structural model of an engine for nanochemistry is obtained. The structural scheme of an engine is constructed. For the control systems in nanochemistry with an elecro elastic engine its characteristics are determined.

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Introduction

An engine with piezoelectric or electrostrictive effect is used in precision control system for nanochemistry [1-6]. In structural schema of electro elastic engine its energy transformation is clearly [7-12]. The piezo engine is applied for precise adjustment for nanochemistry in adaptive optics and scanning microscopy [3-20].

Characteristics of an Engine

For an engine its equations in matrixes [8, 11-38] for nanochemistry have the form

$$\begin{bmatrix} D \end{bmatrix} = \begin{bmatrix} d \end{bmatrix} \begin{bmatrix} T \end{bmatrix} + \begin{bmatrix} \varepsilon^T \end{bmatrix} \begin{bmatrix} E \end{bmatrix}$$
$$\begin{bmatrix} S \end{bmatrix} = \begin{bmatrix} s^E \end{bmatrix} \begin{bmatrix} T \end{bmatrix} + \begin{bmatrix} d \end{bmatrix}^t \begin{bmatrix} E \end{bmatrix}$$

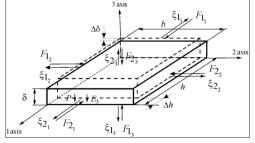
where [D], [S], [d], [T], $[\varepsilon^T]$, [E], $[s^E]$, $[d]^t$ are matrixes

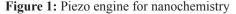
electric induction, relative displacement, piezo coefficient, strength mechanical field, dielectric constant, strength electric field, elastic compliance, transposed piezo coefficient.

For piezo engine Figure 1 its relative displacement for 3 axis [8, 11-20] has the form

$$S_3 = d_{33}E_3 + s_{33}^E T_3$$

where d_{33} is piezo coefficient, E_3 is strength electric field on 3 axis, s_{33}^{E} is elastic compliance, T_3 is strength mechanical field on 3 axis.





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On the mechanical characteristic of longitudinal piezo engine its maximums values the force and the displacement are obtained in the form

$$F_{\max} = d_{33}S_0E_3 / s_{33}^E, \quad \Delta \delta_{\max} = d_{33}\delta E_3 = d_{33}U$$

For $d_{33} = 4 \cdot 10^{-10} \text{ m/V}$, $S_0 = 1.5 \cdot 10^{-4} \text{ m}^2$, $\delta = 2.5 \cdot 10^{-3} \text{ m}$, $s_{33}^E = 15 \cdot 10^{-12} \text{ m}^2/\text{N}$, $E_3 = 0.8 \cdot 10^5 \text{ V/m}$ the maximums values

of the force and the displacement on Figure 2 are obtained

 $F_{\text{max}} = 320 \text{ N}$ and $\Delta \delta_{\text{max}} = 80 \text{ nm}$ with error 10%.

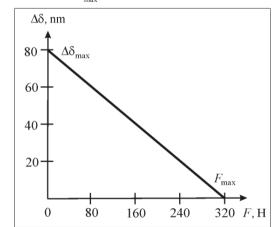


Figure 2: Mechanical characteristic of longitudinal piezo engine for nanochemistry

The differential equation of an electro elastic engine for nanochemistry has the form [11-45]

$$\frac{d^2\Xi(x,s)}{dx^2} - \gamma^2\Xi(x,s) = 0$$

$$\gamma = s/c^{L} + \alpha$$

here $\Xi(x,s)$ is the Laplace transform displacement, s is the parameter, x is the coordinate. The decision this differential equation is determined in the form

$$\Xi(x,s) = Ae^{-x\gamma} + Be^{x\gamma}$$

Using the expressions

$$\Xi(0,s) = \Xi_1(s) \text{ for } x = 0$$

$$\Xi(l,s) = \Xi_2(s) \text{ for } x = l$$

where *l* is length.

We have the coefficients A and B in the form

$$A = \left(\Xi_1 e^{l\gamma} - \Xi_2\right) / \left[2 \operatorname{sh}(l\gamma)\right]$$
$$B = \left(\Xi_2 - \Xi_1 e^{-l\gamma}\right) / \left[2 \operatorname{sh}(l\gamma)\right]$$

The solution equation has form

$$\Xi(x,s) = \{\Xi_1(s) \operatorname{sh}[(l-x)\gamma] + \Xi_2(s) \operatorname{sh}(x\gamma)\}/\operatorname{sh}(l\gamma)$$

For an engine its system of the stresses has the form

$$T_{j}(0,s) = \left(s_{ij}^{\Psi}\right)^{-1} \frac{d\Xi(x,s)}{dx}\Big|_{x=0} - v_{mi}\left(s_{ij}^{\Psi}\right)^{-1} \Psi_{m}(s)$$
$$T_{j}(l,s) = \left(s_{ij}^{\Psi}\right)^{-1} \frac{d\Xi(x,s)}{dx}\Big|_{x=l} - v_{mi}\left(s_{ij}^{\Psi}\right)^{-1} \Psi_{m}(s)$$

where v_{mi} is electro elastic coefficient.

Also the structural model of an engine for Figure 3 has the form

$$\begin{split} &\Xi_{1}(s) = \left(M_{2}s^{2}\right)^{-1} \left\{-F_{1}(s) + \left(\chi_{ij}^{\Psi}\right)^{-1} \begin{bmatrix} v_{mi}\Psi_{m}(s) - [\gamma/\mathrm{sh}(l\gamma)] \\ \times [\mathrm{ch}(l\gamma)\Xi_{1}(s) - \Xi_{2}(s)] \end{bmatrix}\right\} \\ &\Xi_{2}(s) = \left(M_{2}s^{2}\right)^{-1} \left\{-F_{2}(s) + \left(\chi_{ij}^{\Psi}\right)^{-1} \begin{bmatrix} v_{mi}\Psi_{m}(s) - [\gamma/\mathrm{sh}(l\gamma)] \\ \times [\mathrm{ch}(l\gamma)\Xi_{2}(s) - \Xi_{1}(s)] \end{bmatrix}\right\} \end{split}$$

 $\begin{array}{l} \text{where } v_{mi} = \begin{cases} d_{33}, d_{31}, d_{15} \\ g_{33}, g_{31}, g_{15} \end{cases}, \ \Psi_m = \begin{cases} E_3, E_1 \\ D_3, D_1 \end{cases}, \ s^{\Psi}_{ij} = \begin{cases} s^E_{33}, s^E_{11}, s^E_{55} \\ s^B_{33}, s^D_{11}, s^D_{55} \end{cases}, \\ l = \{ \, \delta, \, h, \, b \ , \ \gamma = \{ \gamma^E, \gamma^D \ , \ c^{\Psi} = \{ c^E, c^D \ , \ \chi^{\Psi}_{ij} = s^{\Psi}_{ij} / S_0 \ , \ \text{and} \\ \Psi = E \ \text{or } \Psi = D \ . \end{cases}$

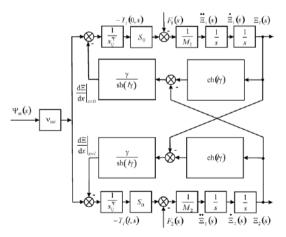


Figure 3: Structural scheme of an engine for nanochemistry

This structural scheme is used for calculation the deformations of the electro elastic engine in nanochemistry. From the structural model the matrix equation has the form

$$\begin{bmatrix} \Xi_1(s) \\ \Xi_2(s) \end{bmatrix} = \begin{bmatrix} W_{11}(s) & W_{12}(s) & W_{13}(s) \\ W_{21}(s) & W_{22}(s) & W_{23}(s) \end{bmatrix} \begin{bmatrix} \Psi_m(s) \\ F_1(s) \\ F_2(s) \end{bmatrix}$$

The steady-state movements of the faces 1 and 2 have the form

$$\xi_{1} = d_{mi}M_{2}l\Psi_{m}/(M_{1} + M_{2})$$

$$\xi_{2} = d_{mi}M_{1}l\Psi_{m}/(M_{1} + M_{2})$$

The steady-state movements of the longitudinal piezo engine have the form

$$\xi_1 = d_{33}M_2U/(M_1 + M_2)$$

$$\xi_2 = d_{33}M_1U/(M_1 + M_2)$$

For U = 200 V, $d_{33} = 4 \cdot 10^{-10}$ m/V, $M_1 = 0.5$ kg, $M_2 = 2$ kg the steady-state movements matter $\xi_1 = 64$ nm, $\xi_2 = 16$ nm, $\xi_1 + \xi_2 = 80$ nm and error 10%.

The steady-state movement of the transverse piezo engine with fixed one face and at elastic-inertial load has the form

$$\Delta h = \frac{d_{31}Uh/\delta}{1+C_l/C_{11}^E}$$

For the transverse piezo engine at elastic-inertial load the expression has the form

$$W(s) = \frac{\Xi(s)}{U(s)} = \frac{d_{31}h/\delta}{\left(1 + C_l/C_{11}^E\right)\left(T_t^2 p^2 + 2T_t\xi_t p + 1\right)}$$
$$T_t = \sqrt{M/(C_l + C_{11}^E)}, \quad \omega_t = 1/T_t$$

where C_l , C_{11}^E are the stiffness of load and engine, T_l , ξ_l , ω_l are the time constant, the attenuation coefficient and the conjugate frequency of the engine. For M = 2 kg, $C_l = 0.2 \cdot 10^7$ N/m, $C_{11}^E = 1 \cdot 10^7$ N/m, we have the time constant $T_l = 0.4 \cdot 10^{-3}$ s and the conjugate frequency of the engine $\omega_l = 2.5 \cdot 10^3$ s⁻¹ with error 10%.

Conclusions

For an engine its structural model for nanochemistry is determined. The structural scheme of an engine is constructed. The characteristics of an engine are obtained.

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